

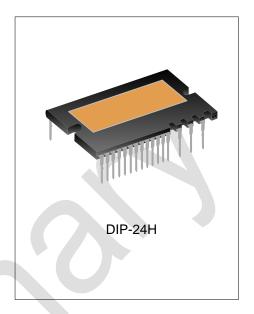
600V/10A 3-PHASE FULL-BRIDGE DRIVER (INTELLIGENT POWER MODULE)

DESCRIPTION

SDM10G60FB is a 3-phase brushless DC motor driver with high integration and high reliability for low power inverter driving such as air conditioner, refrigerator and dishwasher. It has embedded six low-loss IGBTs and three high-speed half-bridge gate drivers with high voltage.

The under voltage, short circuit and over temperature protections integrated make the circuit work safely in a wide range. The current of each phase can be detected separately because there is one independent negative DC terminal for each phase.

SDM10G60FB uses high-insulation design, compact package and carries heat easily, which makes it easy to use especially for compact installation applications.



FEATURES

- Built-in six low-loss 600V/10A IGBT;
- Built-in high-voltage integrated circuit of gate driver;
- Built-in under voltage, over temperature and over current protections;
- Built-in bootstrap diode with current limiting resistor;
- Compatible with 3.3V, 5V MCU interface, active high;
- Three independent negative DC terminal for inverter current detection;
- Alarm signal: for low-side under voltage and short circuit protections;
- Package in Al₂O₃ DBC design with low thermal resistance;
- Insulation level: 1500Vrms/min

APPLICATIONS

- Air conditioner compressor
- Refrigerator compressor
- Low power inverter

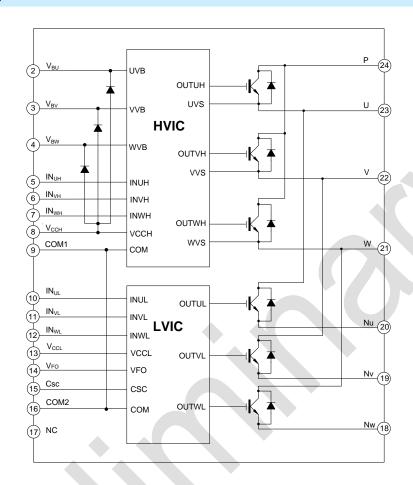
ORDERING INFORMATION

Part	No.	Package	Marking	Material	Packing
SDM10	G60FB	DIP-24H	SDM10G60FB	Pb free	Tube

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BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATING

Characteristics	Symbol	Rating	Unit
Inverter section			
Voltage on the DC bus between PN	V _{PN}	450	V
Surge voltage on the DC bus between PN	V _{PN(Surge)}	500	V
Voltage between collector and emitter	V _{CES}	600	V
Continuous current of the single IGBT collector, T_C =25°C	Ic	10	А
Peak current of the single IGBT collector, T_C =25°C, Pulse width less than 1ms	I _{CP}	20	А
Max. power dissipation of the collector of each module, $T_C=25^{\circ}C$	Pc	25	W
Control section			
Control supply voltage	Vcc	20	V
High-side control voltage	V _{BS}	20	V
Input signal voltage	V _{IN}	-0.5~ V _{CC} +0.5	V
Fault output supply voltage	V_{FO}	-0.5~V _{CC} +0.5	V

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Characteristics	Symbol	Rating	Unit
Fault output current Sink current at V _{FO} pin	I _{FO}	1	mA
Input voltage at current detect pin	V_{SC}	-0.5~V _{CC} +0.5	V
Whole system			
Voltage limit of short circuit protection V _{CC} =V _{BS} =13.5~16.5V, T _J =150°C, single and less than 2µs	V _{PN(PROT)}	400	V
Operating temperature of module case Limit condition: -40°C≤T _J ≤150°C	Tc	-20~100	°C
Storage temperature range	T _{STG}	-40~125	°C
Junction-to-case thermal resistance of each IGBT	$R_{\theta JCQ}$	4.0	°C/W
Junction-to-case thermal resistance of each FRD	R ₀ JCF	5.0	°C/W
Insulation voltage 60Hz, Sine, 1 minute Connect the pin to heatsink	V _{ISO}	1500	V _{rms}
Mounting torque Mounting screws: -M3, 0.62N.m recommended	Т	0.5~0.8	N.m

RECOMMENDED OPERATING CONDITIONS

			Ratings	Ratings		
Characteristics	Symbol	Symbol			Unit	
		Min.	Тур.	Max.		
Voltage on the bus between PN	V_{PN}	-	300	400	V	
Control supply voltage	V _{cc}	13.5	15	16.5	V	
High-side control voltage	V _{BS}	13.5	15	16.5	V	
	dVcc/dt				V/µs	
Control voltage variation	dV _{BS} /dt	-1	-	1		
On threshold voltage	V _{IN(ON)}	3.0	-	Vcc	V	
Off threshold voltage	V _{IN(OFF)}	0	-	0.6	V	
Blanking time for preventing alrm-short $V_{CC}=V_{BS}=13.5\sim16.5V$, $T_{J}\leqslant25^{\circ}C$	T _{dead}	1.5	-	-	μs	
PWM input signal	f _{PWM}	-	-	20	KHz	
COM variation	M	-5		E	V	
(Between COM-Nu,Nv,Nw)	V _{COM}	-5	-	5	V	

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ELECTRICAL CHARACTERISTICS (Unless otherwise specified, Tamb=25°C, VCC=VBS=15V)

Inverter

Characteri	Characteristics		Conditions	Min.	Тур.	Max.	Unit
Saturation voltage between collector and emitter		V _{CE(SAT)}	$V_{CC}=V_{BS}=15V, V_{IN}=5V$ $I_{C}=10A, T_{J}=25^{\circ}C$	-	1.9	2.2	V
FRD forward voltage	ge	V _F	V _{IN} =0V, I _F =10A, T _J = 25°C	-	1.7	2.2	V
		t _{ON}		-	0.60	- 4	μs
		t _{C(ON)}		-	0.20	-	μs
	High side	t _{OFF}	V _{PN} = 300V, V _{CC} = V _{BS} = 15V,	-	0.60	-	μs
		t _{C(OFF)}		-	0.15	·	μs
Switching times		t _{rr}	$I_C = 10A$, $V_{IN} = 0V \longleftrightarrow 5V$,	-	0.06	-	μs
Switching times		t _{ON}	Inductive load	•	0.74	-	μs
		t _{C(ON)}	Refer to fig. 1	-	0.20	-	μs
	Low side	t _{OFF}			0.70	-	μs
		t _{C(OFF)}		-	0.15	-	μs
		t _{rr}		- 1	0.06	-	μs
Leakage current be collector and emitte		I _{CES}	V _{CE} =V _{CES}	-	-	1	mA

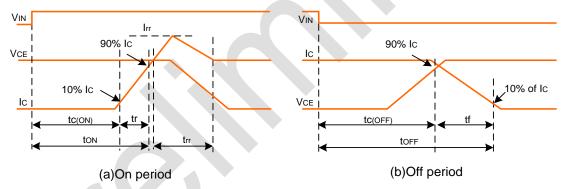


Fig.1 Switching definition

Control section

Characteristics	Symbol	Conditions		Min.	Тур.	Max.	Unit
V _{CC} Quiescent current	I _{QCCN}	V _{CC} =15V, V _{IN} =5V	V _{CCH} -COM, V _{CCL} -COM	-	-	2.8	mA
Voc Quiescent current	I _{QCCF}	V _{CC} =15V, V _{IN} =0V		-	-	2.8	mA
V _{BS} Quiescent current	I _{QBS}	V _{BS} =15V, V _{INH} =0V	$\begin{array}{c} V_{BU}\text{-}V_{SU}, V_{BV}\text{-}V_{SV}, \\ V_{BW}\text{-}V_{SW} \end{array}$	-	-	100	μΑ
V_{FOH} V_{SC} =0V,V _{FO} pull up 10KΩ resistor to 5V		4.9	1	1	V		
	V _{FOL}	V _{SC} =1V,IFo=1	mA	-	1	0.95	V

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Characteristics	Symbol	Conditions		Min.	Тур.	Max.	Unit
Fault output pulse width	t _{FO}	(note1)		20	-	-	us
Trip voltage of short circuit	V _{SC(ref)}	V _{CC} =15V	(note2)	0.43	0.48	0.53	V
Over-temperature protection	TSD	LVIC tempera	ature	100	120	140	°C
Over-temperature protection hysteresis	ΔTSD	LVIC temperature		-	10	-	°C
Low-side under voltage	UV _{CCD}	UV _{CCD} V _{CC} detect voltage		10.3	11.2	12.5	V
protection(fig.4)	UV _{CCR}	V _{CC} reset voltage		10.8	11.7	13.0	V
High-side under voltage	UV _{BSD}	V _{BS} detect voltage		7.0	10.0	12.0	V
protection (fig.5)	UV _{BSR}	V _{BS} reset voltage		7.5	10.5	12.5	V
On threshold voltage	V _{IH}	Logic High	Between input and	-	2.1	2.6	V
Off threshold voltage	VIL	Logic Low	СОМ	0.8	1.3	-	V

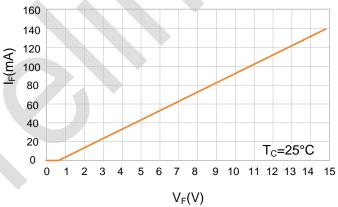
Note1:Fault signal FO outputs when SC or UV protection works. And FO pulse width is different for each protection modes. At SC failure, FO pulse width is a fixed width (=min.20us), but at UV failure, FO outputs continuously until recovering from UV state. (But minimum FO pulse width is 20us.)

Note2: Short circuit protection is functioning only at the low-sides.

Bootstrap Diode Part(Each Bootstrap diode, Unless Otherwise Specified)

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Forward Voltage	V_{F}	I _F =0.1A, T _C =25°C	-	10.7	-	V
Reverse Recovery Time	t _{rr}	I _F =0.1A, T _C =25°C	-	80	-	ns

Built in Bootstrap Diode V_F-I_F Characteristic

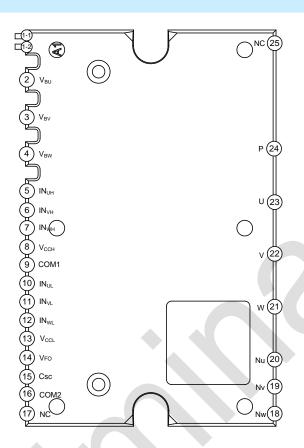


Note: Resistive characteristic: equivalent resistor: ~100 Ω .

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PIN CONFIGURATION



PIN DESCRIPTION

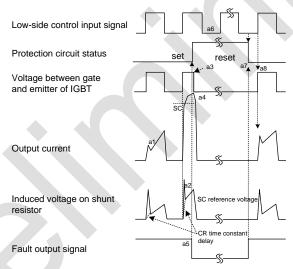
Pin No.	Pin Name	I/O	Pin Descriptions
1-1	(Com)	NC	Inner used terminal, it has control GND potential, should be left no
1-1	(GOIII)	140	connection
1-2	(Vcc)	NC	Inner used terminal, it has control supply potential, should be left no
1 2	(766)	140	connection
2	V_{BU}	1/0	Floating supply voltage for U-phase high-side IGBT driving
3	V_{BV}	I/O	Floating supply voltage for V-phase high-side IGBT driving
4	V_{BW}	I/O	Floating supply voltage for W-phase high-side IGBT driving
5	IN _{UH}	I	U-phase high-side signal input
6	IN _{VH}	I	V-phase high-side signal input
7	IN _{WH}	I	W-phase high-side signal input
8	V _{CCH}	I/O	Supply voltage for high-side gate driver
9	Com1	I/O	Common ground for the module
10	IN _{UL}	I	U-phase low-side signal input
11	IN _{VL}		V-phase low-side signal input
12	IN _{WL}	I	W-phase low-side signal input
13	V _{CCL}	I/O	Supply voltage for low-side gate driver
14	V_{FO}	0	Fault output

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Pin No.	Pin Name	I/O	Pin Descriptions
15	Csc	I/O	Connect to the capacitor for short circuit current detection input and low-pass filter
16	Com2	I/O	Common ground for the module
17	NC	NC	No connection
18	N _W	I/O	W-phase DC negative terminal
19	N _V	I/O	V-phase DC negative terminal
20	N _U	I/O	U-phase DC negative terminal
21	W	0	W-phase output
22	V	0	V-phase output
23	U	0	U-phase output
24	Р	I/O	DC positive terminal
25	NC	NC	No connection

CONTROL TIMING SEQUENCE DESCRIPTION

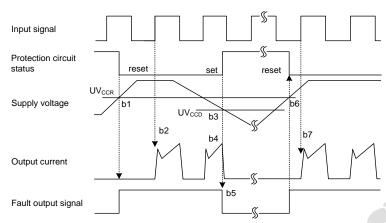


(Including the external shunt resistor and CR connection)

- a1: Normal working: IGBT is on and current is delivered to the load.
- a2: Short circuit current detect(SC trigger) .
- a3: All low-side IGBT gate hard interrupt.
- a4: All low-side IGBT is off.
- a5: Fault output timer starts working for t_{FO} =minimum 20uS.
- a6: Input "L": IGBT is off.
- a7: Input "H": IGBT is on, while during the period when fault output is active, IGBT is not conductive.
- a8: Normal working: IGBT is on and current is delivered to the load.

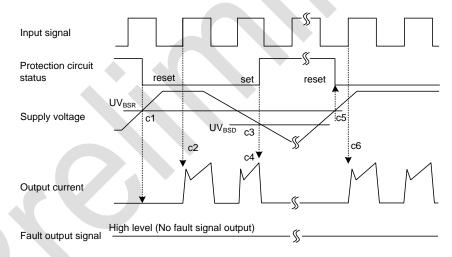
Fig. 2 Short circuit current protection(only for low-side)

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- b1: Supply voltage rises to UV_{CCR} , the circuit begins when next input waveform arrives.
- b2: Normal working: IGBT is on and current is delivered to the load.
- b3: Under voltage detect point (UV_{CCD}).
- b4: All low-side IGBT is off no matter what signal is input.
- b5: Begin to output fault indicating signal for t_{FO}=minimum 20uS.
- b6: Under voltage reset (UV_{CCR}).
- b7: Normal working: IGBT is on and current is delivered to the load.

Fig.3 Under voltage protection(low-side)

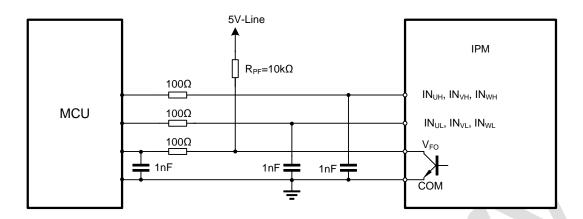


- c1: Supply voltage rises to UVBSR, the circuit begins when next input signal arrives.
- c2: Normal working: IGBT is on and current is delivered to the load.
- c3: Under voltage detect (UVBSD).
- c4: IGBT is off no matter what signal is input, but there is no fault signal output.
- c5: Under voltage reset (UVBSR).
- c6: Normal working: IGBT is on and current is delivered to the load.

Fig.4 Under voltage protection(high-side)

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Note:

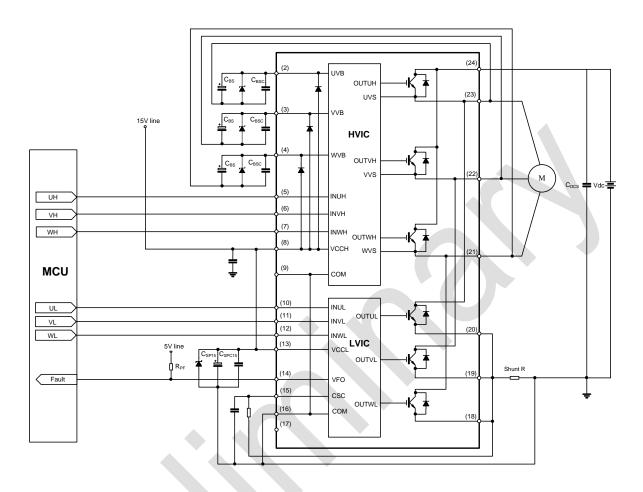
The RC coupling of each input should change following the PWM control solution and the PCB connection impedance. There is a 5K pull-down resistor integrated in IPM input signal section, so, should pay attention on the voltage drop at input terminal when using an external filter resistor.

Fig. 5 MCU input/output connection circuit recommended

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TYPICAL APPLICATION CIRCUIT



Note:

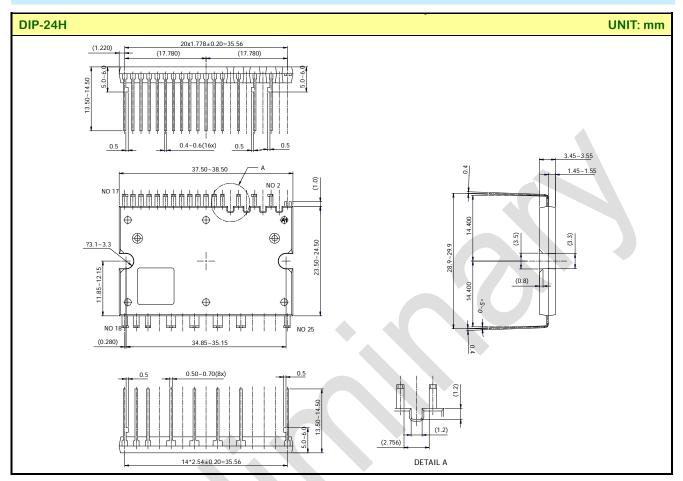
- (1) The routing of each input pin should be as short as possible to avoid the possible error action;
- (2) Input signal is high active and there is a $5K\Omega$ pull-down resistor connected to the ground at input of each channel in the HVIC; In addition, RC filter circuit can be added to the input, which will prevent the surge noise caused by the incorrect input.
- (3) To avoid the surge damage, a flat high-frequency non-inductive capacitor between 0.1μF and 0.22μF should be connected between PN and the routing must be as short as possible;
- (4) The routing between current detect resistor and IPM should be as short as possible to avoid the damage caused by the big surge voltage bringing from the connection inductance.
- (5) A filter capacitor at least 7 times by bootstrap capacitor CBS (CBS is recommended to be more than1µF) is better to be added at the 15V power supply input;
- (6) Each external capacitor must be connected to the pins of IPM as close as possible;
- (7) V_{FO} output is open, it should be pulled up to a 5V supply with a resistor that make Ifo up to 1mA
- (8) In short circuit protection circuit, please select the time constant of RF and CSC between 1.5~2μs, at the same time, the routing around the RF and CSC should be as short as possible. The wiring of Rf should be near the terminal of shunt resistor.

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