

EiceDRIVER™

1ED020I12-F2

Single IGBT Driver IC

Final Data Sheet

Rev. 2.0, 2011-08-01

Asic & Power ICs

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## 1 Overview

### Main Features

- Single channel isolated IGBT Driver
- For 600V/1200 V IGBTs
- 2 A rail-to-rail output
- Vcesat-detection
- Active Miller Clamp

### Product Highlights

- Coreless transformer isolated driver
- Galvanic Insulation
- Integrated protection features
- Suitable for operation at high ambient temperature

### Typical Application

- AC and Brushless DC Motor Drives
- High Voltage DC/DC-Converter
- UPS-Systems
- Welding

### Description

The 1ED020I12-F2 is a galvanic isolated single channel IGBT driver in PG-DSO-16-15 package that provides an output current capability of typically 2A.

All logic pins are 5V CMOS compatible and could be directly connected to a microcontroller.

The data transfer across galvanic isolation is realized by the integrated Coreless Transformer Technology.

The 1ED020I12-F2 provides several protection features like IGBT desaturation protection, active Miller clamping and active shut down.



| Product Name | Gate Drive Current | Package      |
|--------------|--------------------|--------------|
| 1ED020I12-F2 | ±2 A               | PG-DSO-16-15 |

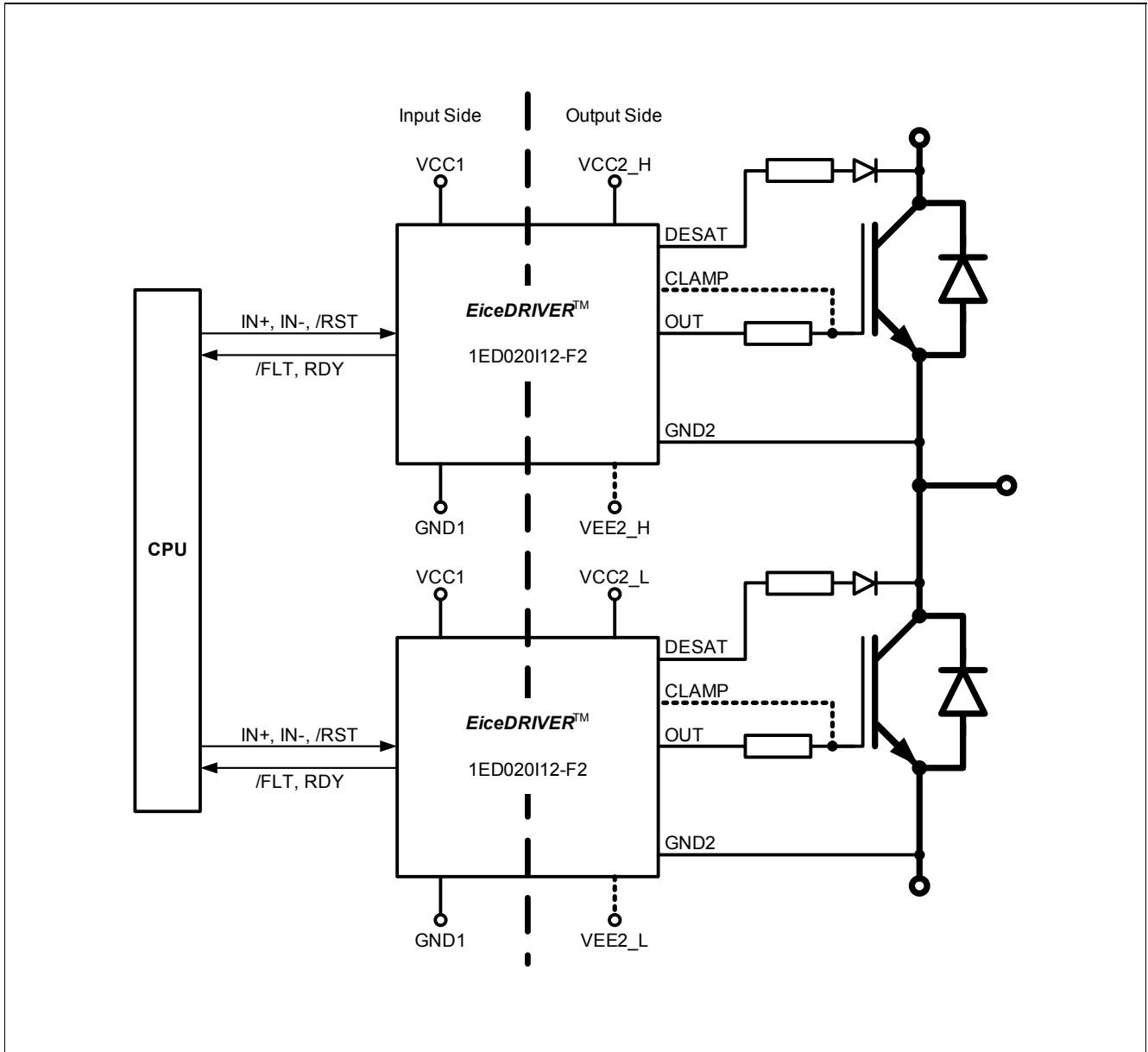


Figure 1 Typical Application



## 2 Block Diagram

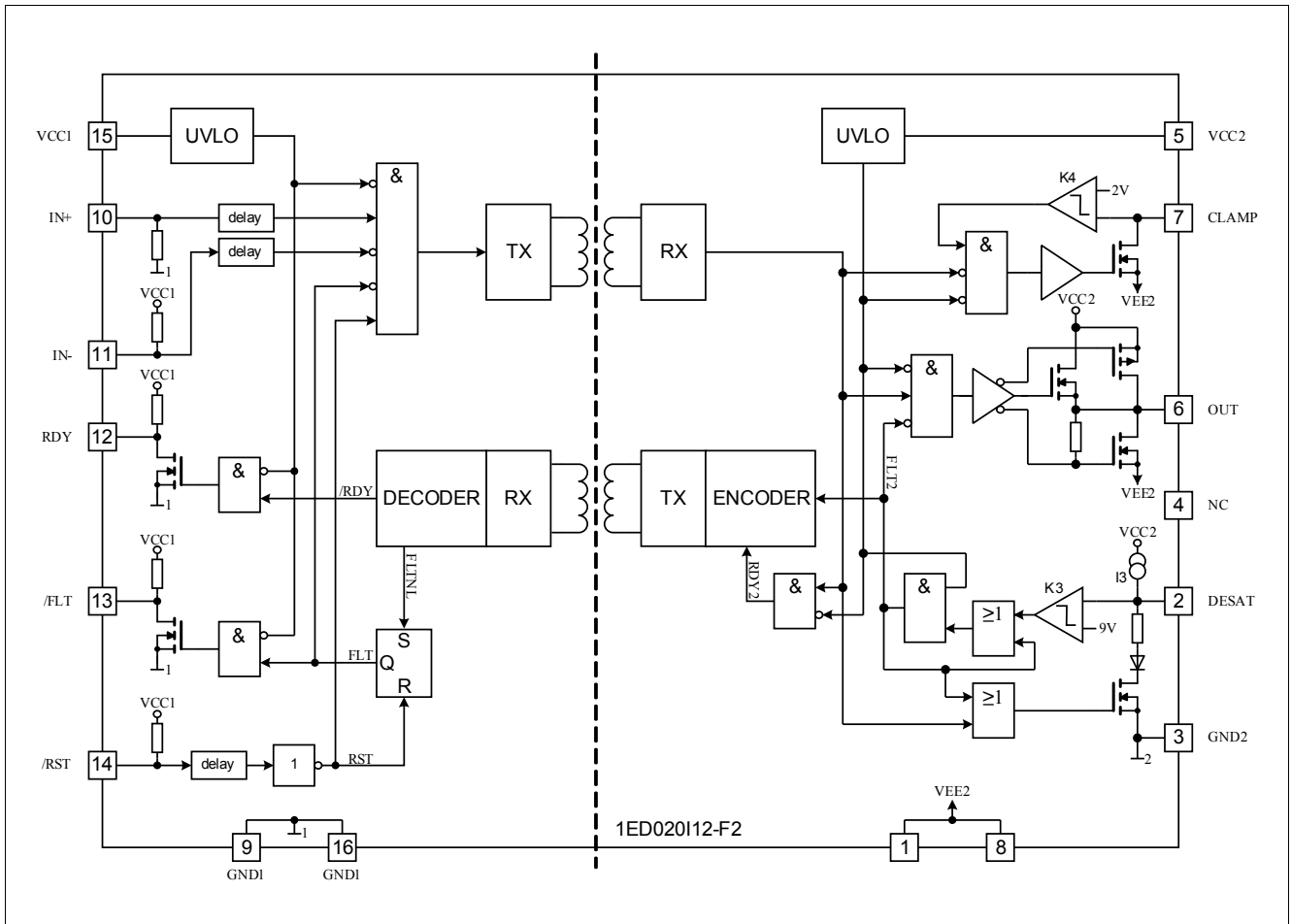


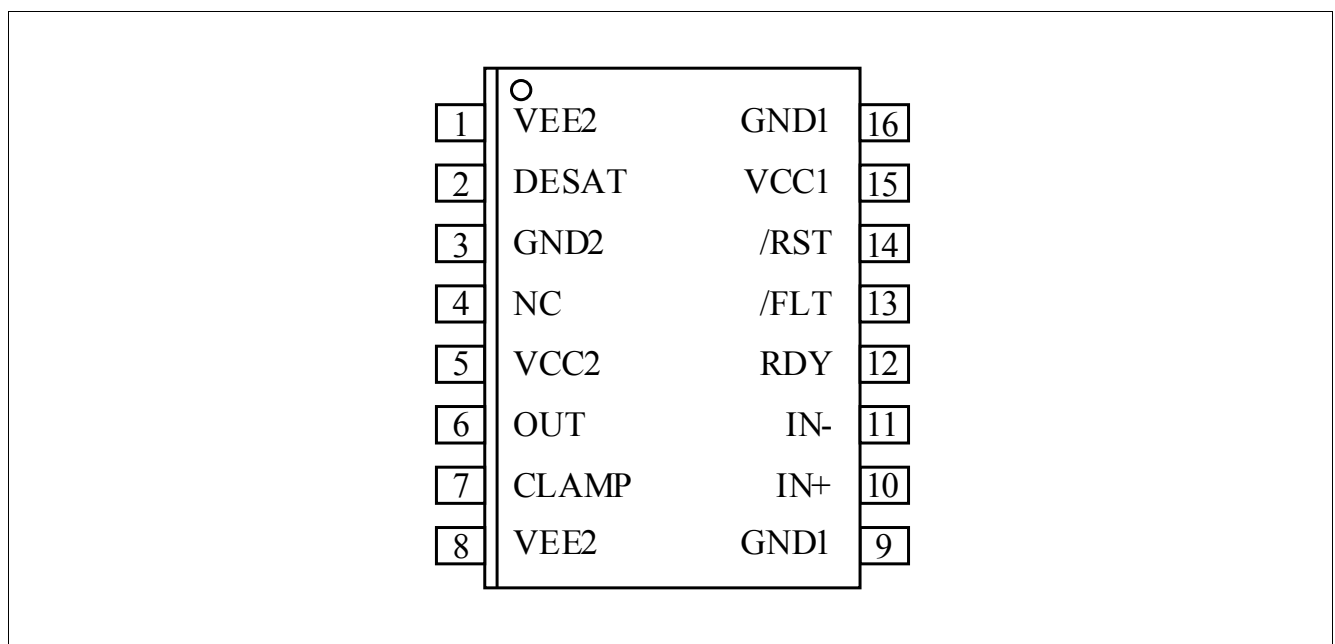
Figure 2 Block Diagram 1ED020112-F2

### 3 Pin Configuration and Functionality

#### 3.1 Pin Configuration

**Table 1 Pin Configuration**

| Pin No. | Name  | Function                          |
|---------|-------|-----------------------------------|
| 1       | VEE2  | Negative power supply output side |
| 2       | DESAT | Desaturation protection           |
| 3       | GND2  | Signal ground output side         |
| 4       | NC    | Not connected                     |
| 5       | VCC2  | Positive power supply output side |
| 6       | OUT   | Driver output                     |
| 7       | CLAMP | Miller clamping                   |
| 8       | VEE2  | Negative power supply output side |
| 9       | GND1  | Ground input side                 |
| 10      | IN+   | Non inverted driver input         |
| 11      | IN-   | Inverted driver input             |
| 12      | RDY   | Ready output                      |
| 13      | FLT   | Fault output, low active          |
| 14      | RST   | Reset input, low active           |
| 15      | VCC1  | Positive power supply input side  |
| 16      | GND1  | Ground input side                 |



**Figure 3 PG-DSO-16-15 (top view)**

## 3.2 Pin Functionality

### GND1

Ground connection of the input side.

### IN+ Non Inverting Driver Input

IN+ control signal for the driver output if IN- is set to low. (The IGBT is on if IN+ = high and IN- = low)

A minimum pulse width is defined to make the IC robust against glitches at IN+. An internal Pull-Down-Resistor ensures IGBT Off-State.

### IN- Inverting Driver Input

IN- control signal for driver output if IN+ is set to high. (IGBT is on if IN- = low and IN+ = high)

A minimum pulse width is defined to make the IC robust against glitches at IN-. An internal Pull-Up-Resistor ensures IGBT Off-State.

### /RST Reset Input

**Function 1:** Enable/shutdown of the input chip. (The IGBT is off if /RST = low). A minimum pulse width is defined to make the IC robust against glitches at /RST.

**Function 2:** Resets the DESAT-FAULT-state of the chip if /RST is low for a time  $T_{RST}$ . An internal Pull-Up-Resistor is used to ensure /FLT status output.

### /FLT Fault Output

Open-drain output to report a desaturation error of the IGBT (FLT is low if desaturation occurs)

### RDY Ready Status

Open-drain output to report the correct operation of the device (RDY = high if both chips are above the UVLO level and the internal chip transmission is faultless).

### VCC1

5 V power supply of the input chip

### VEE2

Negative power supply pins of the output chip. If no negative supply voltage is available, all VEE2 pins have to be connected to GND2.

### DESAT Desaturation Detection Input

Monitoring of the IGBT saturation voltage ( $V_{CE}$ ) to detect desaturation caused by short circuits. If OUT is high,  $V_{CE}$  is above a defined value and a certain blanking time has expired, the desaturation protection is activated and the IGBT is switched off. The blanking time is adjustable by an external capacitor.

### CLAMP Miller Clamping

Ties the gate voltage to ground after the IGBT has been switched off at a defined voltage to avoid a parasitic switch-on of the IGBT. During turn-off, the gate voltage is monitored and the clamp output is activated when the gate voltage goes below 2 V below VEE2.

**GND2 Reference Ground**

Reference ground of the output chip.

**OUT Driver Output**

Output pin to drive an IGBT. The voltage is switched between VEE2 and VCC2. In normal operating mode Vout is controlled by IN+, IN- and /RST. During error mode (UVLO, internal error or DESAT) Vout is set to VEE2 independent of the input control signals.

**VCC2**

Positive power supply pin of the output side.

## 4 Functional Description

### 4.1 Introduction

The 1ED020I12-F2 is an advanced IGBT dual gate driver that can be also used for driving power MOS devices. Control and protection functions are included to make possible the design of high reliability systems.

The device consists of two galvanic separated parts. The input chip can be directly connected to a standard 5 V DSP or microcontroller with CMOS in/output and the output chip is connected to the high voltage side.

The rail-to-rail driver outputs enables the user to provide easy clamping of the IGBTs gate voltage during short circuit of the IGBT. So an increase of short circuit current due to the feedback via the Miller capacitance can be avoided. Further, a rail-to-rail output reduces power dissipation.

The device also includes IGBT desaturation protection with FAULT status outputs.

Two READY status outputs reports if the device is supplied and operates correctly.

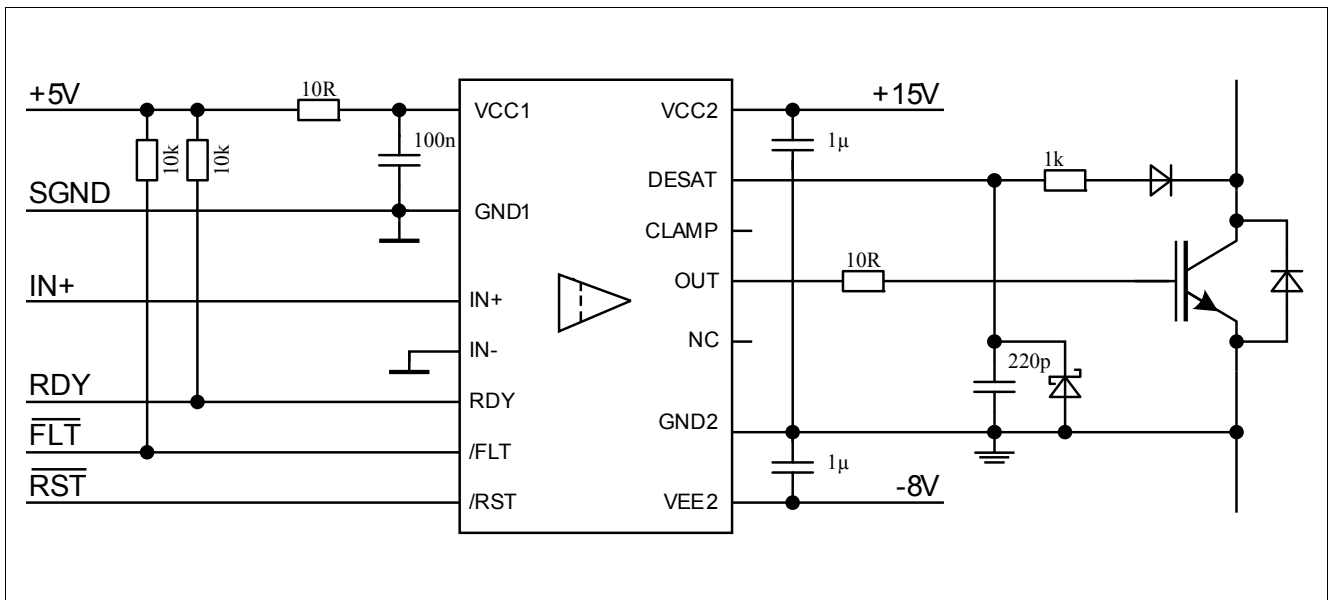


Figure 4 Application Example Bipolar Supply

### 4.2 Supply

The driver 1ED020I12-F2 is designed to support two different supply configurations, bipolar supply and unipolar supply.

In bipolar supply the driver is typically supplied with a positive voltage of 15V at VCC2 and a negative voltage of -8V at VEE2, please refer to [Figure 4](#). Negative supply prevents a dynamic turn on due to the additional charge which is generated from IGBT input capacitance times negative supply voltage. If an appropriate negative supply voltage is used, connecting CLAMP to IGBT gate is redundant and therefore typically not necessary.

For unipolar supply configuration the driver is typically supplied with a positive voltage of 15V at VCC2. Erratically dynamic turn on of the IGBT could be prevented with active Miller clamp function, so CLAMP output is directly connected to IGBT gate, please refer to [Figure 5](#).

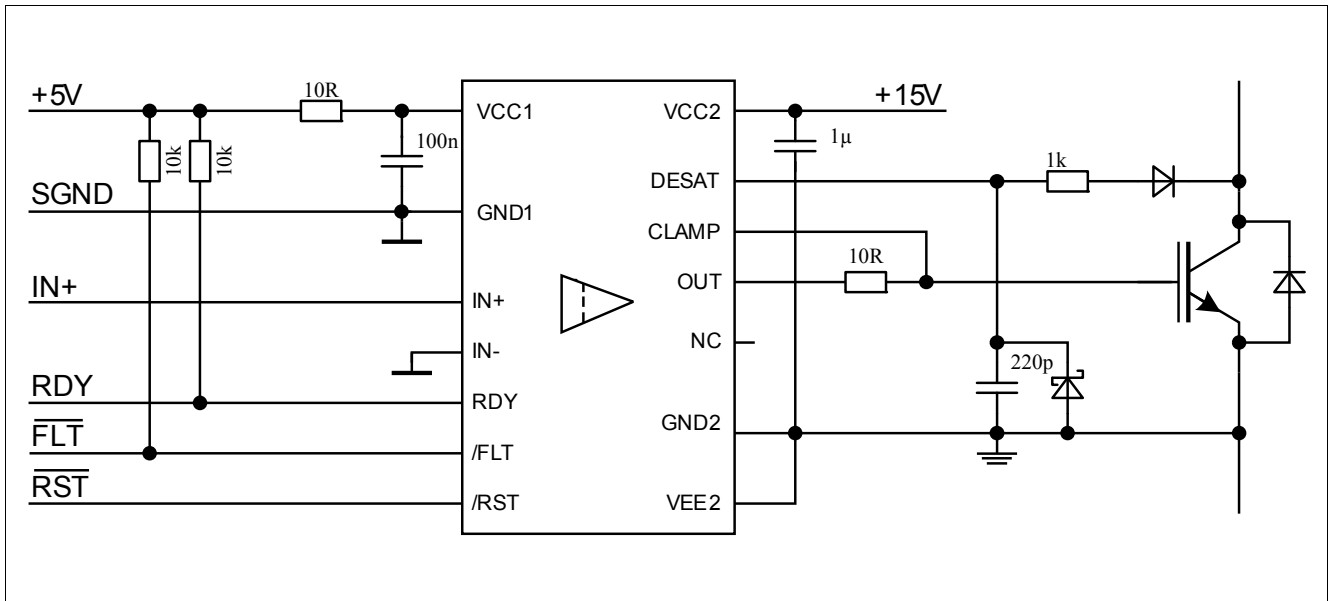


Figure 5 Application Example Unipolar Supply

## 4.3 Internal Protection Features

### 4.3.1 Undervoltage Lockout (UVLO)

To ensure correct switching of IGBTs the device is equipped with an undervoltage lockout for both chips, refer to [Figure 9](#).

If the power supply voltage  $V_{VCC1}$  of the input chip drops below  $V_{UVLO1}$  a turn-off signal is sent to the output chip before power-down. The IGBT is switched off and the signals at IN+ and IN- are ignored as long as  $V_{VCC1}$  reaches the power-up voltage  $V_{UVLOH1}$ .

If the power supply voltage  $V_{VCC2}$  of the output chip goes down below  $V_{UVLO2}$  the IGBT is switched off and signals from the input chip are ignored as long as  $V_{VCC2}$  reaches the power-up voltage  $V_{UVLOH2}$ . VEE2 is not monitored, otherwise negative supply voltage range from 0 V to -12 V would not be possible.

### 4.3.2 READY Status Output

The READY outputs shows the status of three internal protection features.

- UVLO of the input chip
- UVLO of the output chip after a short delay
- Internal signal transmission after a short delay

It is not necessary to reset the READY signal since its state only depends on the status of the former mentioned protection signals.

### 4.3.3 Watchdog Timer

During normal operation the internal signal transmission is monitored by a watchdog timer. If the transmission fails for a given time, the IGBT is switched off and the READY output reports an internal error.

### 4.3.4 Active Shut-Down

The Active Shut-Down feature ensures a safe IGBT off-state if the output chip is not connected to the power supply, IGBT gate is clamped at OUT to VEE2.

## 4.4 Non-Inverting and Inverting Inputs

There are two possible input modes to control the IGBT. At non-inverting mode IN+ controls the driver output while IN- is set to low. At inverting mode IN- controls the driver output while IN+ is set to high, please see [Figure 7](#). A minimum input pulse width is defined to filter occasional glitches.

## 4.5 Driver Outputs

The output driver sections uses only MOSFETs to provide a rail-to-rail output. This feature permits that tight control of gate voltage during on-state and short circuit can be maintained as long as the drivers supply is stable. Due to the low internal voltage drop, switching behaviour of the IGBT is predominantly governed by the gate resistor. Furthermore, it reduces the power to be dissipated by the driver.

## 4.6 External Protection Features

### 4.6.1 Desaturation Protection

A desaturation protection ensures the protection of the IGBT at short circuit. When the DESAT voltage goes up and reaches 9 V, the output is driven low. Further, the FAULT output is activated, please refer to [Figure 8](#). A programmable blanking time is used to allow enough time for IGBT saturation. Blanking time is provided by a highly precise internal current source and an external capacitor.

### 4.6.2 Active Miller Clamp

In a half bridge configuration the switched off IGBT tends to dynamically turn on during turn on phase of the opposite IGBT. A Miller clamp allows sinking the Miller current across a low impedance path in this high dV/dt situation. Therefore in many applications, the use of a negative supply voltage can be avoided.

During turn-off, the gate voltage is monitored and the clamp output is activated when the gate voltage goes below typical 2 V (related to VEE2). The clamp is designed for a Miller current up to 2 A.

### 4.6.3 Short Circuit Clamping

During short circuit the IGBTs gate voltage tends to rise because of the feedback via the Miller capacitance. An additional protection circuit connected to OUT and CLAMP limits this voltage to a value slightly higher than the supply voltage. A current of maximum 500 mA for 10  $\mu$ s may be fed back to the supply through one of this paths. If higher currents are expected or a tighter clamping is desired external Schottky diodes may be added.

## 4.7 RESET

The reset inputs have two functions.

Firstly, /RST is in charge of setting back the FAULT output. If /RST is low longer than a given time, /FLT will be cleared at the rising edge of /RST, refer to [Figure 8](#); otherwise, it will remain unchanged. Moreover, it works as enable/shutdown of the input logic, refer to [Figure 7](#).

## 5 Electrical Parameters

### 5.1 Absolute Maximum Ratings

Note: Absolute maximum ratings are defined as ratings, which when being exceeded may lead to destruction of the integrated circuit. Unless otherwise noted all parameters refer to GND1.

**Table 2 Absolute Maximum Ratings**

| Parameter  | Symbol          | Values         |                       | Unit    | Note / Test Condition            |
|--|-----------------|----------------|-----------------------|---------|----------------------------------|
|  |                 | Min.           | Max.                  |         |                                  |
| Positive power supply output side                                  | $V_{VCC2}$      | -0.3           | 20                    | V       | 1)                               |
| Negative power supply output side                                  | $V_{VEE2}$      | -12            | 0.3                   | V       | 1)                               |
| Maximum power supply voltage output side ( $V_{VCC2} - V_{VEE2}$ ) | $V_{max2}$      | –              | 28                    | V       | –                                |
| Gate driver output   | $V_{OUT}$       | $V_{VEE2}-0.3$ | $V_{max2}+0.3$        | V       | –                                |
| Gate driver high output maximum current                            | $I_{OUT}$       | –              | 2.4                   | A       | $t = 2 \mu s$                    |
| Gate & Clamp driver low output maximum current                     | $I_{OUT}$       | –              | 2.4                   | A       | $t = 2 \mu s$                    |
| Maximum short circuit clamping time                                | $t_{CLP}$       | –              | 10                    | $\mu s$ | $I_{CLAMP/OUT} = 500 \text{ mA}$ |
| Positive power supply input side                                   | $V_{VCC1}$      | -0.3           | 6.5                   | V       | –                                |
| Logic input voltages (IN+, IN-, RST)                               | $V_{LogicIN}$   | -0.3           | 6.5                   | V       | –                                |
| Open-drain Logic output voltage ( $\overline{FLT}$ )               | $V_{FLT\#}$     | -0.3           | 6.5                   | V       | –                                |
| Open-drain Logic output voltage (RDY)                              | $V_{RDY}$       | -0.3           | 6.5                   | V       | –                                |
| Open-drain Logic output current ( $\overline{FLT}$ )               | $I_{FLT\#}$     | –              | 10                    | mA      | –                                |
| Open-drain Logic output current (RDY)                              | $I_{RDY}$       | –              | 10                    | mA      | –                                |
| Pin DESAT voltage  | $V_{DESAT}$     | -0.3           | $V_{VCC2} + 0.3$      | V       | 1)                               |
| Pin CLAMP voltage  | $V_{CLAMP}$     | -0.3           | $V_{VCC2} + 0.3^{2)}$ | V       | 3)                               |
| Input to output isolation voltage (GND2)                           | $V_{ISO}$       | -1200          | 1200                  | V       |                                  |
| Junction temperature   | $T_J$           | -40            | 150                   | °C      | –                                |
| Storage temperature  | $T_S$           | -55            | 150                   | °C      | –                                |
| Power dissipation, per input part                                  | $P_{D, IN}$     | –              | 100                   | mW      | 4) @ $T_A = 25^\circ C$          |
| Power dissipation, per output part                                 | $P_{D, OUT}$    | –              | 700                   | mW      | 4) @ $T_A = 25^\circ C$          |
| Thermal resistance (Input part)                                    | $R_{THJA, IN}$  | –              | 160                   | K/W     | 4) @ $T_A = 25^\circ C$          |
| Thermal resistance (Output chip active)                            | $R_{THJA, OUT}$ | –              | 125                   | K/W     | 4) @ $T_A = 25^\circ C$          |
| ESD Capability   | $V_{ESD}$       | –              | 1                     | kV      | Human Body Model <sup>5)</sup>   |

1) With respect to GND2.



**Electrical Parameters/Operating Parameters**

- 2) May be exceeded during short circuit clamping.
- 3) With respect to VEE2.
- 4) Output IC power dissipation is derated linearly at 8.5 mW/°C above 62°C. Input IC power dissipation does not require derating. See **Figure 11** for reference layouts for these thermal data. Thermal performance may change significantly with layout and heat dissipation of components in close proximity.
- 5) According to EIA/JESD22-A114-B (discharging a 100 pF capacitor through a 1.5 kΩ series resistor).

## 5.2 Operating Parameters

*Note: Within the operating range the IC operates as described in the functional description. Unless otherwise noted all parameters refer to GND1.*

**Table 3 Operating Parameters**

| Parameter   | Symbol          | Values         |                 | Unit  | Note / Test Condition |
|---|-----------------|----------------|-----------------|-------|-----------------------|
|   |                 | Min.           | Max.            |       |                       |
| Positive power supply output side                                     | $V_{VCC2}$      | 13             | 20              | V     | 1)                    |
| Negative power supply output side                                     | $V_{VEE2}$      | -12            | 0               | V     | 1)                    |
| Maximum power supply voltage output side<br>( $V_{VCC2} - V_{VEE2}$ ) | $V_{max2}$      | –              | 28              | V     | –                     |
| Positive power supply input side                                      | $V_{VCC1}$      | 4.5            | 5.5             | V     | –                     |
| Logic input voltages (IN+, IN-, RST)                                  | $V_{LogicIN}$   | -0.3           | 5.5             | V     | –                     |
| Pin CLAMP voltage   | $V_{CLAMP}$     | $V_{VEE2}-0.3$ | $V_{VCC2}^{2)}$ | V     | –                     |
| Pin DESAT voltage   | $V_{DESAT}$     | -0.3           | $V_{VCC2}$      | V     | 1)                    |
| Pin TLSET voltage   | $V_{TLSET}$     | -0.3           | $V_{VCC2}$      | V     | 1)                    |
| Ambient temperature   | $T_A$           | -40            | 105             | °C    | –                     |
| Common mode transient immunity <sup>3)</sup>                          | $ dV_{ISO}/dt $ | –              | 50              | kV/μs | @ 500 V               |

1) With respect to GND2.

2) May be exceeded during short circuit clamping.

3) The parameter is not subject to production test - verified by design/characterization

## 5.3 Recommended Operating Parameters

*Note: Unless otherwise noted all parameters refer to GND1.*

**Table 4 Recommended Operating Parameters**

| Parameter                         | Symbol     | Value | Unit | Note / Test Condition |
|-----------------------------------|------------|-------|------|-----------------------|
| Positive power supply output side | $V_{VCC2}$ | 15    | V    | 1)                    |
| Negative power supply output side | $V_{VEE2}$ | -8    | V    | 1)                    |
| Positive power supply input side  | $V_{VCC1}$ | 5     | V    | –                     |

1) With respect to GND2.

## 5.4 Electrical Characteristics

Note: The electrical characteristics include the spread of values in supply voltages, load and junction temperatures given below. Typical values represent the median values at  $T_A = 25^\circ\text{C}$ . Unless otherwise noted all voltages are given with respect to their respective GND (GND1 for pins 9 to 16, GND2 for pins 1 to 8).

### 5.4.1 Voltage Supply

**Table 5 Voltage Supply**

| Parameter   | Symbol       | Values |      |      | Unit | Note / Test Condition   |
|---|--------------|--------|------|------|------|---|
|   |              | Min.   | Typ. | Max. |      |   |
| UVLO Threshold Input Chip                                 | $V_{UVLOH1}$ | –      | 4.1  | 4.3  | V    | –   |
|   | $V_{UVLOH1}$ | 3.5    | 3.8  | –    | V    | –   |
| UVLO Hysteresis Input Chip ( $V_{UVLOH1} - V_{UVLOL1}$ )  | $V_{HYS1}$   | 0.15   | –    | –    | V    | –   |
| UVLO Threshold Output Chip                                | $V_{UVLOH2}$ | –      | 12.0 | 12.6 | V    | –   |
|   | $V_{UVLOL2}$ | 10.4   | 11.0 | –    | V    | –   |
| UVLO Hysteresis Output Chip ( $V_{UVLOH1} - V_{UVLOL1}$ ) | $V_{HYS2}$   | 0.7    | 0.9  | –    | V    | –   |
| Quiescent Current Input Chip                              | $I_{Q1}$     | –      | 7    | 9    | mA   | $V_{VCC1} = 5\text{ V}$<br>IN+ = High,<br>IN- = Low<br>=>OUT = High,<br>RDY = High,<br>/FLT = High                              |
| Quiescent Current Output Chip                             | $I_{Q2}$     | –      | 4    | 6    | mA   | $V_{VCC2} = 15\text{ V}$<br>$V_{VEE2} = -8\text{ V}$<br>IN+ = High,<br>IN- = Low<br>=>OUT = High,<br>RDY = High,<br>/FLT = High |

**5.4.2 Logic Input and Output**
**Table 6 Logic Input and Output**

| Parameter   | Symbol  | Values |      |      | Unit          | Note / Test Condition  |
|---|---|--------|------|------|---------------|--|
|   |   | Min.   | Typ. | Max. |               |  |
| IN+,IN-, $\overline{\text{RST}}$ Low Input Voltage                  | $V_{\text{IN+L}}$ ,<br>$V_{\text{IN-L}}$ ,<br>$V_{\text{RSTL\#}}$ | –      | –    | 1.5  | V             | –  |
| IN+,IN-, $\overline{\text{RST}}$ High Input Voltage                 | $V_{\text{IN+H}}$ ,<br>$V_{\text{IN-H}}$ ,<br>$V_{\text{RSTH\#}}$ | 3.5    | –    | –    | V             | –  |
| IN-, $\overline{\text{RST}}$ Input Current                          | $I_{\text{IN-}}$ , $I_{\text{RST\#}}$                             | –      | 100  | 400  | $\mu\text{A}$ | $V_{\text{IN-}} = \text{GND1}$<br>$V_{\text{RST\#}} = \text{GND1}$ |
| IN+ Input Current   | $I_{\text{IN+}}$  | –      | 100  | 400  | $\mu\text{A}$ | $V_{\text{IN+}} = \text{VCC1}$                                     |
| RDY, $\overline{\text{FLT}}$ Pull Up Current                        | $I_{\text{PRDY}}$ , $I_{\text{PFLT\#}}$                           | –      | 100  | 400  | $\mu\text{A}$ | $V_{\text{RDY}} = \text{GND1}$<br>$V_{\text{FLT\#}} = \text{GND1}$ |
| Input Pulse Suppression IN+, IN-                                    | $T_{\text{MININ+}}$ ,<br>$T_{\text{MININ-}}$                      | 30     | 40   | –    | ns            | –  |
| Input Pulse Suppression $\overline{\text{RST}}$ for ENABLE/SHUTDOWN | $T_{\text{MINRST}}$   | 30     | 40   | –    | ns            | –  |
| Pulse Width $\overline{\text{RST}}$ for Reseting FLT                | $T_{\text{RST}}$  | 800    | –    | –    | ns            | –  |
| $\overline{\text{FLT}}$ Low Voltage                                 | $V_{\text{FLTL}}$   | –      | –    | 300  | mV            | $I_{\text{SINK(FLT\#)}} = 5 \text{ mA}$                            |
| RDY Low Voltage   | $V_{\text{RDYL}}$   | –      | –    | 300  | mV            | $I_{\text{SINK(RDY)}} = 5 \text{ mA}$                              |

### 5.4.3 Gate Driver

**Table 7 Gate Driver**

| Parameter                      | Symbol             | Values                 |                          |                          | Unit | Note / Test Condition  |
|--------------------------------|--------------------|------------------------|--------------------------|--------------------------|------|--|
|                                |                    | Min.                   | Typ.                     | Max.                     |      |  |
| High Level Output Voltage      | $V_{\text{OUTH1}}$ | $V_{\text{CC2}} - 1.2$ | $V_{\text{CC2}} - 0.8$   | –                        | V    | $I_{\text{OUTH}} = -20 \text{ mA}$   |
|                                | $V_{\text{OUTH2}}$ | $V_{\text{CC2}} - 2.5$ | $V_{\text{CC2}} - 2.0$   | –                        | V    | $I_{\text{OUTH}} = -200 \text{ mA}$  |
|                                | $V_{\text{OUTH3}}$ | $V_{\text{CC2}} - 9$   | $V_{\text{CC2}} - 5$     | –                        | V    | $I_{\text{OUTH}} = -1 \text{ A}$   |
|                                | $V_{\text{OUTH4}}$ |                        | $V_{\text{CC2}} - 10$    | –                        | V    | $I_{\text{OUTH}} = -2 \text{ A}$   |
| High Level Output Peak Current | $I_{\text{OUTH}}$  | -1.5                   | -2.0                     | –                        | A    | IN+ = High,<br>IN- = Low;<br>OUT = High  |
| Low Level Output Voltage       | $V_{\text{OUTL1}}$ | –                      | $V_{\text{VEE2}} + 0.04$ | $V_{\text{VEE2}} + 0.09$ | V    | $I_{\text{OUTL}} = 20 \text{ mA}$  |
|                                | $V_{\text{OUTL2}}$ | –                      | $V_{\text{VEE2}} + 0.3$  | $V_{\text{VEE2}} + 0.85$ | V    | $I_{\text{OUTL}} = 200 \text{ mA}$   |
|                                | $V_{\text{OUTL3}}$ | –                      | $V_{\text{VEE2}} + 2.1$  | $V_{\text{VEE2}} + 5$    | V    | $I_{\text{OUTL}} = 1 \text{ A}$  |
|                                | $V_{\text{OUTL4}}$ | –                      | $V_{\text{VEE2}} + 7$    | –                        | V    | $I_{\text{OUTL}} = 2 \text{ A}$  |
| Low Level Output Peak Current  | $I_{\text{OUTL}}$  | 1.5                    | 2.0                      | –                        | A    | IN+ = Low,<br>IN- = Low;<br>OUT = Low,<br>$V_{\text{VCC2}} = 15 \text{ V}$ ,<br>$V_{\text{VEE2}} = -8 \text{ V}$ |

### 5.4.4 Active Miller Clamp

**Table 8 Active Miller Clamp**

| Parameter               | Symbol               | Values |                          |                          | Unit | Note / Test Condition              |
|-------------------------|----------------------|--------|--------------------------|--------------------------|------|------------------------------------|
|                         |                      | Min.   | Typ.                     | Max.                     |      |                                    |
| Low Level Clamp Voltage | $V_{\text{CLAMPL1}}$ | –      | $V_{\text{VEE2}} + 0.03$ | $V_{\text{VEE2}} + 0.08$ | V    | $I_{\text{OUTL}} = 20 \text{ mA}$  |
|                         | $V_{\text{CLAMPL2}}$ | –      | $V_{\text{VEE2}} + 0.3$  | $V_{\text{VEE2}} + 0.8$  | V    | $I_{\text{OUTL}} = 200 \text{ mA}$ |
|                         | $V_{\text{CLAMPL3}}$ | –      | $V_{\text{VEE2}} + 1.9$  | $V_{\text{VEE2}} + 4.8$  | V    | $I_{\text{OUTL}} = 1 \text{ A}$    |
| Low Level Clamp Current | $I_{\text{CLAMPL}}$  | 2      | –                        | –                        | A    | <sup>1)</sup>                      |
| Clamp Threshold Voltage | $V_{\text{CLAMP}}$   | 1.6    | 2.1                      | 2.4                      | V    | Related to VEE2                    |

1) The parameter is not subject to production test - verified by design/characterization

### 5.4.5 Short Circuit Clamping

**Table 9 Short Circuit Clamping**

| Parameter   | Symbol         | Values |      |      | Unit | Note / Test Condition   |
|---|----------------|--------|------|------|------|---|
|   |                | Min.   | Typ. | Max. |      |   |
| Clamping voltage (OUT)<br>( $V_{OUT} - V_{VCC2}$ )      | $V_{CLPout}$   | –      | 0.8  | 1.3  | V    | IN+ = High,<br>IN- = Low,<br>OUT = High<br>$I_{OUT} = 500$ mA<br>pulse test,<br>$t_{CLPmax} = 10$ $\mu$ s)    |
| Clamping voltage<br>(CLAMP) ( $V_{VCLAMP} - V_{VCC2}$ ) | $V_{CLPclamp}$ | –      | 1.3  | –    | V    | IN+ = High, IN- =<br>Low,<br>OUT = High<br>$I_{CLAMP} = 500$ mA<br>(pulse test,<br>$t_{CLPmax} = 10$ $\mu$ s) |
| Clamping voltage<br>(CLAMP)                             | $V_{CLPclamp}$ | –      | 0.7  | 1.1  | V    | IN+ = High, IN- =<br>Low,<br>OUT = High<br>$I_{CLAMP} = 20$ mA  |

### 5.4.6 Dynamic Characteristics

Dynamic characteristics are measured with  $V_{VCC1} = 5$  V,  $V_{VCC2} = 15$  V and  $V_{VEE2} = -8$  V.

**Table 10 Dynamic Characteristics**

| Parameter   | Symbol        | Values |      |      | Unit    | Note / Test Condition   |
|---|---------------|--------|------|------|---------|---|
|   |               | Min.   | Typ. | Max. |         |   |
| Input IN to output propa-<br>gation delay ON  | $T_{PDON}$    | 145    | 170  | 195  | ns      | $C_{LOAD} = 100$ pF<br>$V_{IN+} = 50\%$ ,<br>$V_{OUT} = 50\%$ @ 25°C        |
| Input IN to output propa-<br>gation delay OFF   | $T_{PDOFF}$   | 145    | 165  | 190  | ns      |   |
| Input IN to output propa-<br>gation delay distortion<br>( $T_{PDOFF} - T_{PDON}$ )                        | $T_{PDISTO}$  | -35    | -5   | 25   | ns      |   |
| IN input to output<br>propagation delay ON<br>variation due to temp                                       | $T_{PDONT}$   | –      | –    | 25   | ns      | <sup>1)</sup> $C_{LOAD} = 100$ pF<br>$V_{IN+} = 50\%$ ,<br>$V_{OUT} = 50\%$ |
| IN input to output<br>propagation delay OFF<br>variation due to temp                                      | $T_{PDONT}$   | –      | –    | 35   | $\mu$ s | <sup>1)</sup> $C_{LOAD} = 100$ pF<br>$V_{IN+} = 50\%$ ,<br>$V_{OUT} = 50\%$ |
| IN input to output<br>propagation delay<br>distortion variation due to<br>temp ( $T_{PDOFF} - T_{PDON}$ ) | $T_{PDISTOt}$ | –      | –    | 20   | ns      | <sup>1)</sup> $C_{LOAD} = 100$ pF<br>$V_{IN+} = 50\%$ ,<br>$V_{OUT} = 50\%$ |

**Table 10 Dynamic Characteristics (cont'd)**

| Parameter | Symbol     | Values |      |      | Unit | Note / Test Condition                              |
|-----------|------------|--------|------|------|------|--|
|           |            | Min.   | Typ. | Max. |      |  |
| Rise Time | $T_{RISE}$ | 10     | 30   | 60   | ns   | $C_{LOAD} = 1 \text{ nF}$<br>$V_L 10\%, V_H 90\%$  |
|           |            | 200    | 400  | 800  | ns   | $C_{LOAD} = 34 \text{ nF}$<br>$V_L 10\%, V_H 90\%$ |
| Fall Time | $T_{FALL}$ | 10     | 50   | 90   | ns   | $C_{LOAD} = 1 \text{ nF}$<br>$V_L 10\%, V_H 90\%$  |
|           |            | 200    | 350  | 600  | ns   | $C_{LOAD} = 34 \text{ nF}$<br>$V_L 10\%, V_H 90\%$ |

1) The parameter is not subject to production test - verified by design/characterization

### 5.4.7 Desaturation Protection

**Table 11 Desaturation Protection**

| Parameter                            | Symbol         | Values |      |      | Unit          | Note / Test Condition   |
|--------------------------------------|----------------|--------|------|------|---------------|---|
|                                      |                | Min.   | Typ. | Max. |               |   |
| Blanking Capacitor Charge Current    | $I_{DESATC}$   | 450    | 500  | 550  | $\mu\text{A}$ | $V_{VCC2} = 15 \text{ V}$ ,<br>$V_{VEE2} = -8 \text{ V}$<br>$V_{DESAT} = 2 \text{ V}$ |
| Blanking Capacitor Discharge Current | $I_{DESATD}$   | 9      | 14   | –    | mA            | $V_{VCC2} = 15 \text{ V}$ ,<br>$V_{VEE2} = -8 \text{ V}$<br>$V_{DESAT} = 6 \text{ V}$ |
| Desaturation Reference Level         | $V_{DESAT}$    | 8.3    | 9    | 9.5  | V             | $V_{VCC2} = 15 \text{ V}$   |
| Desaturation Filter Time             | $T_{DESATleb}$ | –      | 250  | –    | ns            | $V_{VCC2} = 15 \text{ V}$ ,<br>$V_{VEE2} = -8 \text{ V}$<br>$V_{DESAT} = 9 \text{ V}$ |
| Desaturation Sense to OUT Low Delay  | $T_{DESATOUT}$ | –      | 350  | 430  | ns            | $V_{OUT} = 90\%$<br>$C_{LOAD} = 1 \text{ nF}$   |
| Desaturation Sense to FLT Low Delay  | $T_{DESATFLT}$ | –      | –    | 2.25 | $\mu\text{s}$ | $V_{FLT\#} = 10\%$ ;<br>$I_{FLT\#} = 5 \text{ mA}$                                    |
| Desaturation Low Voltage             | $V_{DESATL}$   | 0.4    | 0.6  | 0.95 | V             | IN+ = Low, IN- = Low,<br>OUT = Low  |
| Leading edge blanking                | $T_{DESATleb}$ | –      | 400  | –    | ns            | Not subject of production test  |

### 5.4.8 Active Shut Down

**Table 12 Active Shut Down**

| Parameter                | Symbol           | Values |      |      | Unit | Note / Test Condition                           |
|--------------------------|------------------|--------|------|------|------|---|
|                          |                  | Min.   | Typ. | Max. |      |   |
| Active Shut Down Voltage | $V_{ACTSD}^{1)}$ | –      | –    | 2.0  | V    | $I_{OUT} = -200 \text{ mA}$ ,<br>$V_{CC2}$ open |

1) With reference to VEE2

## 6 Timing Diagrams

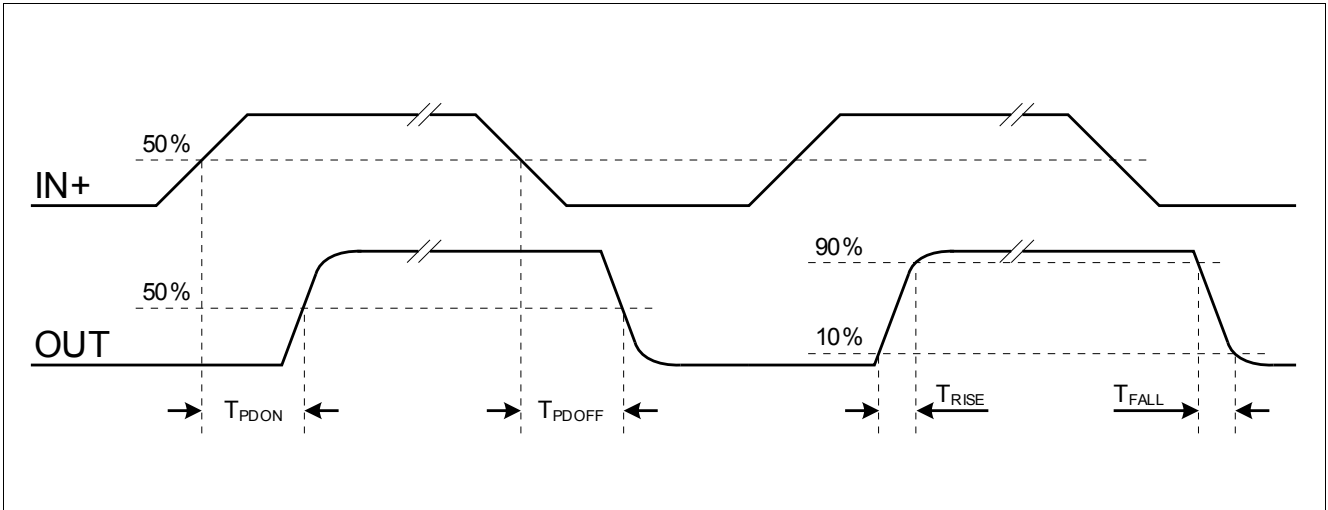


Figure 6 Propagation Delay, Rise and Fall Time

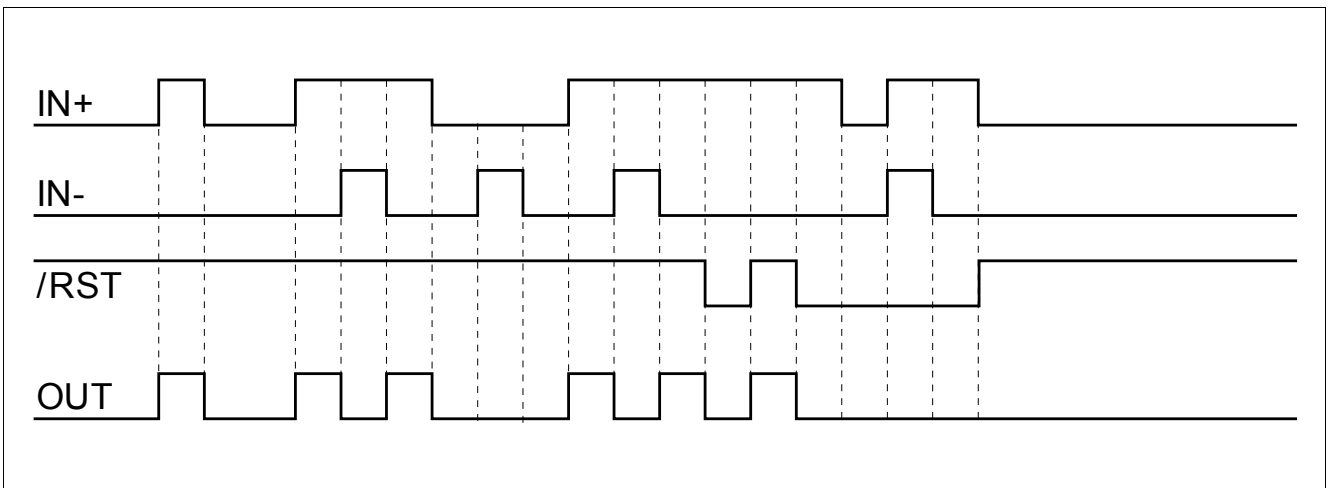


Figure 7 Typical Switching Behavior



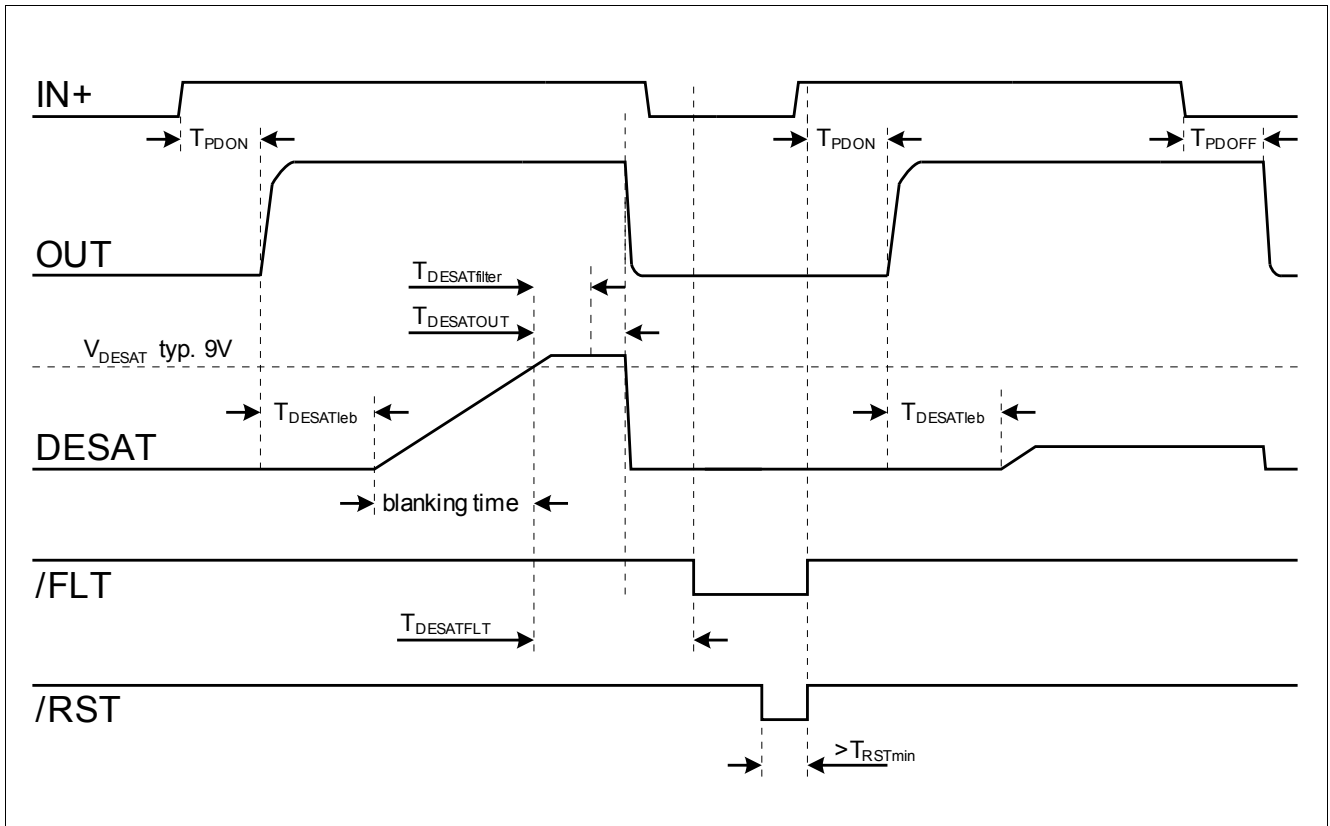


Figure 8 DESAT Switch-Off Behavior

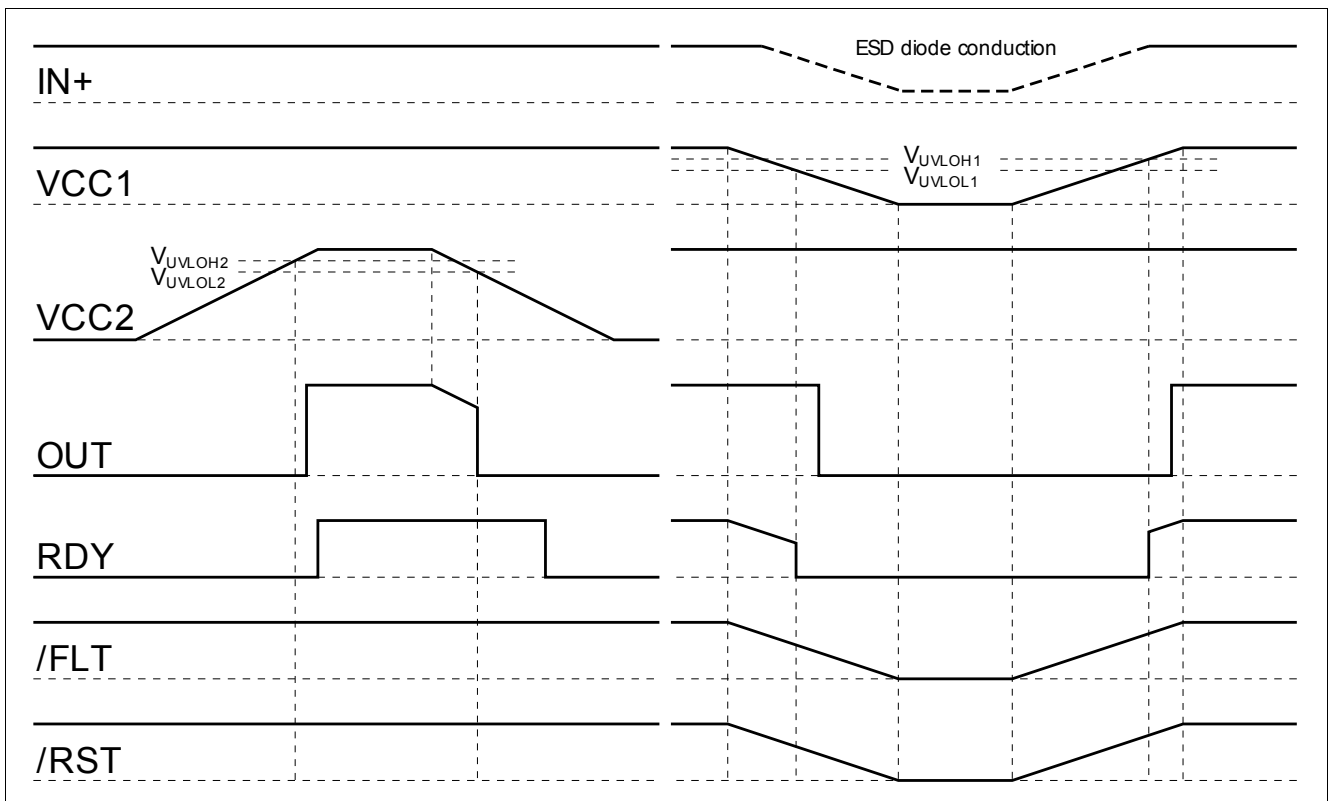


Figure 9 UVLO Behavior



## 8 Application Notes

### 8.1 Reference Layout for Thermal Data

The PCB layout shown in [Figure 11](#) represents the reference layout used for the thermal characterisation. Pins 9 and 16 (GND1) and pins 1 and 8 (VEE2) require ground plane connections for achieving maximum power dissipation. The 1ED020I12-F2 is conceived to dissipate most of the heat generated through this pins.

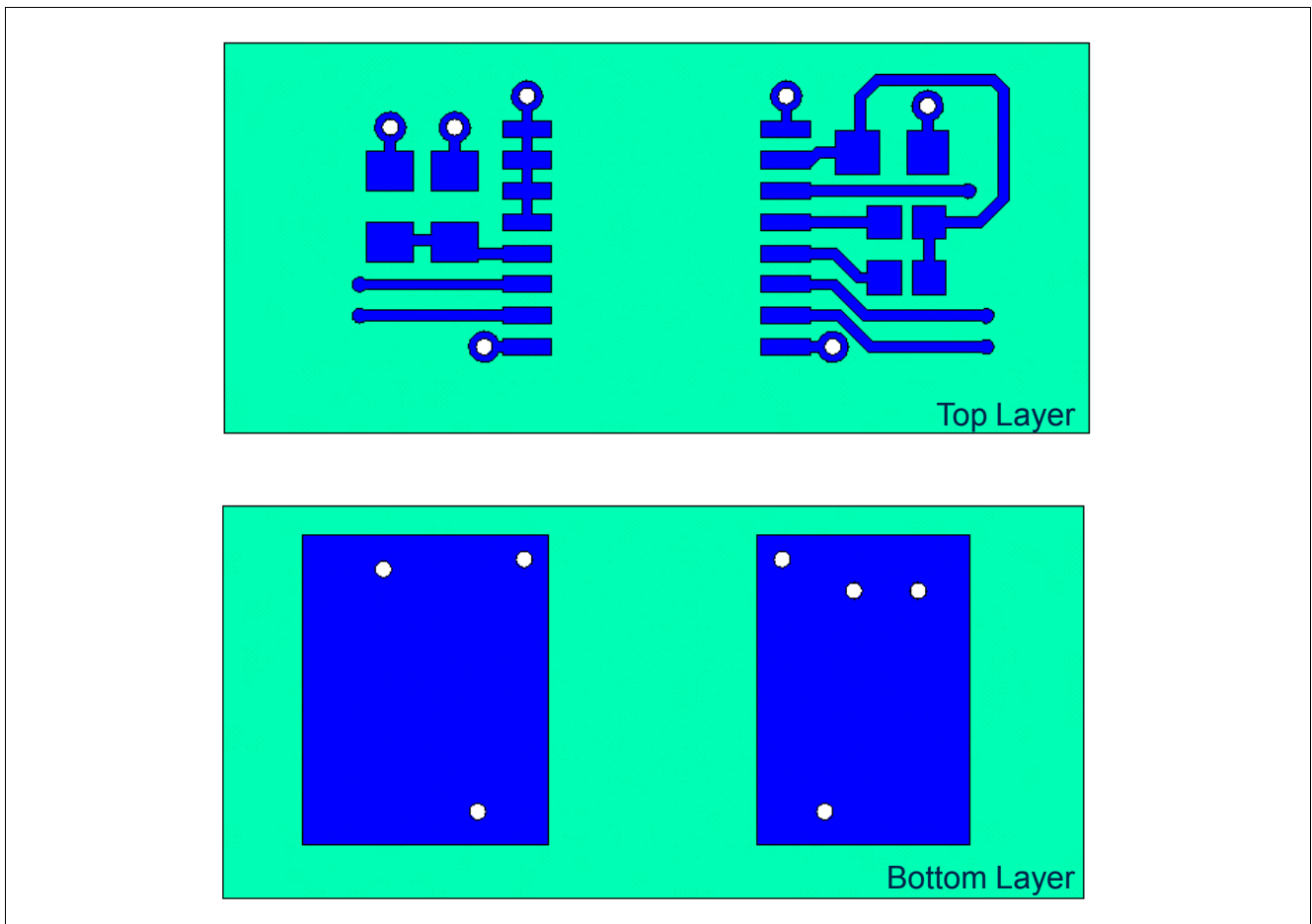


Figure 11 Reference Layout for Thermal Data (Copper thickness 102 µm)

### 8.2 Printed Circuit Board Guidelines

Following factors should be taken into account for an optimum PCB layout.

- Sufficient spacing should be kept between high voltage isolated side and low voltage side circuits.
- The same minimum distance between two adjacent high-side isolated parts of the PCB should be maintained to increase the effective isolation and reduce parasitic coupling.
- In order to ensure low supply ripple and clean switching signals, bypass capacitor trace lengths should be kept as short as possible.
- Lowest trace length for VEE2 to GND2 decoupling could be achieved with capacitor closed to pins 1 and 3.

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